

# Embedded Intelligent Systems Languages and Tools: Dlib

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# Dlib-ml: A Machine Learning Toolkit

- ◇ General purpose cross-platform open source library
- ◇ Written in C++ but with a Python API
- ◇ Built to be as portable and easy to use as possible without further installation or configuration or extra packages needed
  - ◇ Works on OS X, MS Windows, Linux, Solaris, the BSDs, and HP-UX
- ◇ King, D. E. (2009). Dlib-ml: A machine learning toolkit. *The Journal of Machine Learning Research*, 10, 1755-1758.

# Library content categories

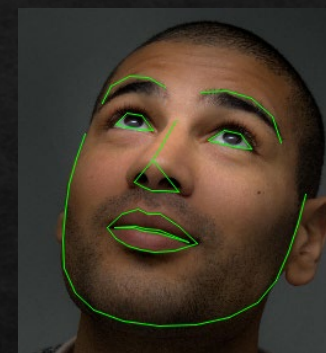
- ◇ Really general purpose:
  - ◇ Algorithms (maths and other that does not fit other categories)
  - ◇ API Wrappers
  - ◇ Bayesian Nets
  - ◇ Compression
  - ◇ Containers
  - ◇ Graph Tools
  - ◇ **Image Processing**
  - ◇ Linear algebra
  - ◇ **Machine Learning**
  - ◇ Metaprogramming
  - ◇ Miscellaneous
  - ◇ Networking
  - ◇ Optimization
  - ◇ Parsing

# Image Processing Tools

- ◇ Basic Pixel functions and structures
  - ◇ `assign_pixel`, `bgr_pixel`, `rgb_pixel`
- ◇ Image I/O
  - ◇ `Load_image`, `load_png`, `save_bmp...`
- ◇ Object Detection
  - ◇ `Find_candidate_object_locations`, `remove_unobtainable_rectangles`, traditional object detector based on hog and pyramids  
Linear algebra

# Image Processing Tools

- ◇ Feature Extraction
  - ◇ HOG, lbp, histograms, find keypoints, SURF, shape\_predictor...
- ◇ Edges and Thresholds
  - ◇ Find\_bright\_lines, find\_dark\_lines, sobel, hough\_transform...
- ◇ Morphology
  - ◇ Close, open, dilation, erosion, union, find\_line\_endpoints, label\_connected\_blobs...



# Image Processing Tools

- ◇ Filtering
  - ◇ Gaussian\_blur, max\_filter, sum\_filter, apply custom filters...
- ◇ Scaling and Rotating
  - ◇ Flip images, rotate, resize, create image pyramids, random jittering
- ◇ Visualization
  - ◇ Draw lines, rectangles, circles, keypoints, heatmaps, HOG features... On images
- ◇ Miscellaneous
  - ◇ Wrapper for OpenCV images, histogram equalization, image padding...

# Machine Learning Tools

- ◇ Binary and Multiclass classification
  - ◇ Mostly SVMs, but also tools like `one_vs_all_trainer`, `one_vs_one_trainer`
- ◇ Regression
  - ◇ RF, MLP, SVM...
- ◇ Clustering
  - ◇ `Chinese_whispers`, `kkmeans`, `nearest_center...`
- ◇ Unsupervised and Semi-Supervised, and Reinforcement Learning

# Machine Learning Tools

- ◇ Other tools
  - ◇ Feature selection, validation, data IO...
- ◇ Deep Learning
  - ◇ Basic tools that allows to create, load, train NNs, and to create predictions with them
  - ◇ Each network is form by three components:
    - ◇ Input\_layer, Computational layers, and a loss layer.



# Conclusions

## ◆ Pros:

- ◆ Self-contained. Capable of coding whole apps with just one light library without extra packages.
- ◆ Many different functionalities
- ◆ Compartmentalized and transparent with the methods

## ◆ Cons:

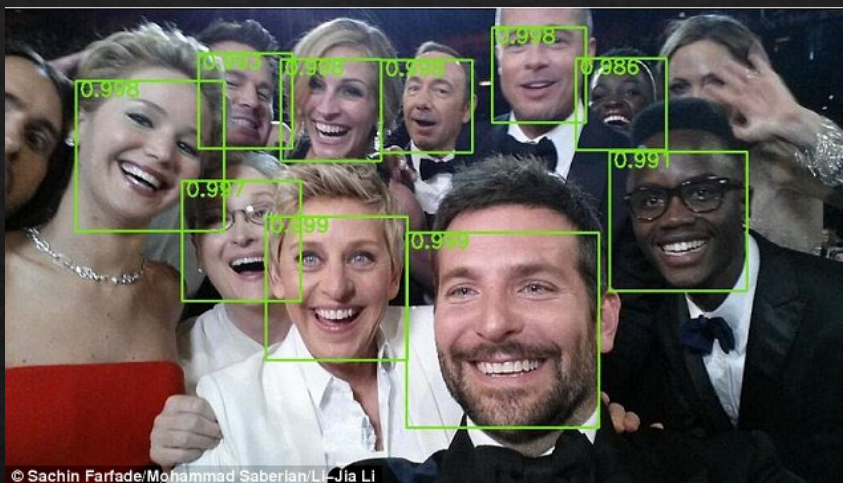
- ◆ «Jack of all trades, master of none.» Decent, but probably not the best in any form
- ◆ Bloated library. Many similar functions with slightly different behaviors

# Lab case: Face Biometrics

- ◇ Face detection
- ◇ Landmark detection
- ◇ Face alignment
- ◇ Face data augmentation
- ◇ Face recognition
- ◇ Applications (drowsiness detection)



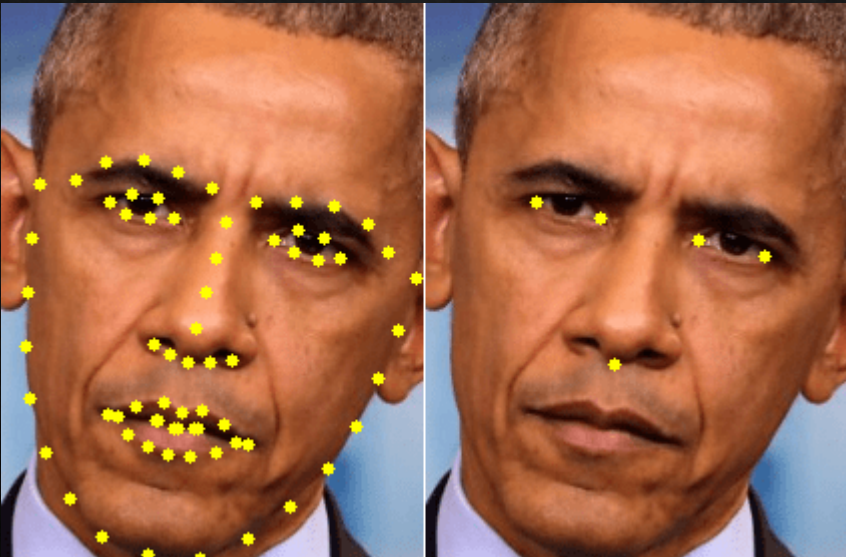
# Face Detection



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- ◇ Is there a face in the image? How many, and where?
- ◇ Dlib provides 2 different face detectors
  - ◇ One is based on traditional object detector method (HOG+classifier over pyramid image)
    - ◇ `Detector = dlib.get_frontal_face_detector()`
  - ◇ The other is based on CNNs
    - ◇ `Detector = dlib.cnn_face_detection_model_v1("model_file.dat")`
- ◇ `Dets = Detector(img,1)`

# Landmark Detection



- ◇ Extract the landmark points of the face in the image
- ◇ Dlib provides 2 different face landmark detectors/predictor
  - ◇ One is just to extract 5 points. Both eye corners and nose center
    - ◇ `sp = dlib.shape_predictor(shape_predictor_5_face_landmarks.dat)`
  - ◇ The other is 68 points across the face
    - ◇ `sp = dlib.shape_predictor(shape_predictor_68_face_landmarks.dat)`
- ◇ `Landmarks = sp(img, detected_face)`

# Face alignment



- ◇ Align faces to improve recognition
  - ◇ Detect faces
  - ◇ Extract landmarks
  - ◇ align
- ◇ You can implement your own alignment method
- ◇ Dlib provides some functions for this
  - ◇ `Aligned = dlib.get_face_chips(img, landmarks_per_face, other parameters)`

# Data augmentation

- ◇ Dlib provides out-of-the-box functions to perform data augmentation. Doing random rotation, scaling, translation and flips.
- ◇ `Aug_data = dlib.jitter_image(image, num_jitters)`

# Face recognition

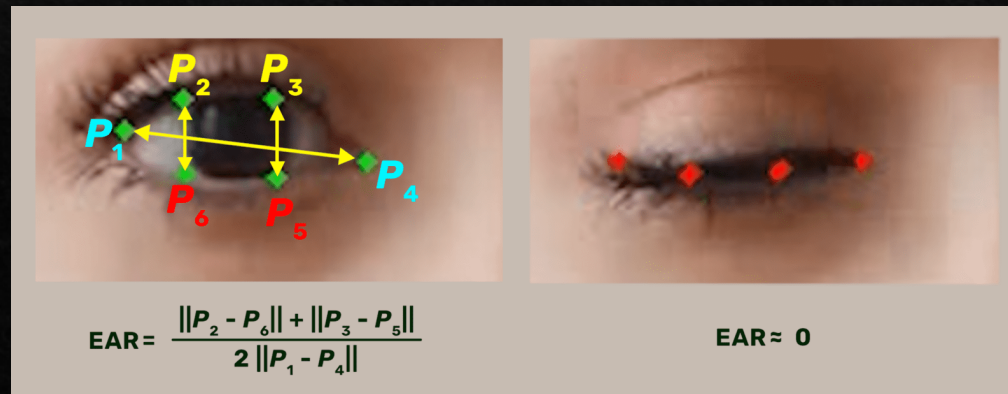
Obama



- ◇ Recognition process
  - ◇ Detect faces
  - ◇ Extract landmarks
  - ◇ Align
  - ◇ Perform face recognition
- ◇ You can implement your own recognition method with dlib functions:
  - ◇ Feature extraction methods: LBP, HOG, SURF...
  - ◇ Classification methods: SVMs, NN...
- ◇ Dlib provides a specific face recognition CNN model based on resnet
  - ◇ `Facerec = dlib.face_recognition_model_v1(model.dat)`

# Application drowsiness detection

- ◇ A simple approach to detect drowsiness while driving is monitoring eye closure.
- ◇ We saw/will see how to extract landmark points that include the eye shape
- ◇ There is a metric called Eye Aspect Ratio (EAR) as shown below
- ◇ Monitoring how many frames in a video the eye is closed or mostly closed can help detect drowsiness





Thanks!  
Questions?



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